

On the Asymptotic Properties of the Inequality Constrained Generalized Least-Squares Estimation

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I. Introduction

There are growing demands to use prior and sample information for parameter estimation of a regression model. Several studies were done to meet such demands by Chipman-Rao [1], Theil [12,13], Judge-Takayama [5], Liew [7,8], Zellner [14], and Rothenberg [10].

The generalized least-squares estimation introduced by Zellner-Theil [15] and Jorgenson [4] reduces to indirect, two-stage and three-stage estimation depending on the identifiability condition and prior assumption on the covariance matrix of the residuals. This paper extends the generalized least-squares estimation so that it can cope with prior information and sample data, and it is called inequality constrained generalized least-squares (ICGLS) estimation. This paper also investigates the statistical properties of the ICGLS estimator and its covariance matrix in the case of a sufficiently large sample. Finally, it provides a numerical example of the ICGLS estimator.

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II. Model

Consider a complete system of p linear structural equations, all of which are identifiable, and suppose that the reduced form exists. Such a system of equations can be estimated by the generalized least-squares estimation model (Zellner-Theil [15], Jorgenson [4], and Madansky [9]).

$$\bar{X}'y = \bar{X}'Z\delta + \bar{X}'\varepsilon \tag{1}$$

where y , δ , ε are vectors of jointly dependent variables, parameters, and residuals of the model respectively. X is a matrix of exogeneous variables of the model and \bar{X} is $(I \times X)$ where I is an identity matrix and \times is a Kronecker product.

The matrix Z is defined as below:

$$Z = \begin{pmatrix} Z_1 & \cdot & 0 \\ & \cdot & \\ 0 & \cdot & Z_p \end{pmatrix}$$

where $Z_i = [Y_i : X_i]$ for $i=1, \dots, p$.

The Y_i and X_i are matrices of explanatory endogeneous and exogeneous variables of i th structural equation.

We assume;

- (i) X is a fixed matrix
- (ii) X has a full rank
- (iii) $E(\varepsilon) = 0$
- (iv) $V(\varepsilon) = \Omega \equiv (\Sigma \times I)$

where Σ is a symmetric positive definite matrix and 0 denotes a null vector.

With sample data, we wish to minimize the weighted sum of squares of the residuals in terms of d by restricting the conditions;

$$Ad \geq c \text{ where } d \text{ is an estimate of } \delta. \tag{1}$$

The estimation problem can be formulated by the following primal-dual relations;

Primal

$$\text{Min } R = (1/2) (\bar{X}'y - \bar{X}'Zd)' \Omega^{-1} (\bar{X}'y - \bar{X}'Zd)$$

subject to

(1) Any mixed system can be converted to the inequality constraints; see Liew[7].

$$Ad \geq c$$

or

$$Ad - v = c \quad (2)$$

where v is a non-negative m -components surplus vector and d is otherwise unrestricted in sign.

Dual

$$\text{Max}_{\lambda} Q = c'\lambda + (1/2)(y'\bar{X}\Omega^{-1}\bar{X}'y - d'BZd)$$

subject to

$$A'\lambda + By = BZd \quad (3)$$

where

$$B \equiv Z'\bar{X}\Omega^{-1}\bar{X}' \quad (4)$$

and λ is an m -components dual vector and d is a solution to the primal problem.

The primal-dual relations reduce to the Dantzig-Cottle [2, 3] fundamental problem.

$$v = W\lambda + q \quad (5)$$

subject to

$$v'\lambda = 0, v \geq 0 \text{ and } \lambda \geq 0 \quad (6)$$

where

$$W = A(BZ)^{-1}A' \quad (7)$$

$$q = Ad^* - c \quad (8)$$

$$d^* = (BZ)^{-1}By \quad (9)$$

and d^* is the generalized least-squares estimator.⁽²⁾

Given q and W , the Dantzig-Cottle optimal solution becomes;

$$\begin{pmatrix} v \\ \lambda \end{pmatrix} = \begin{pmatrix} M_1 \\ \dots \\ M_2 \end{pmatrix} \cdot q \quad (10)$$

where $\begin{pmatrix} v \\ \lambda \end{pmatrix}$ is an m -components vector of the basic variables at optimal solution and

$$\begin{pmatrix} M_1 \\ \dots \\ M_2 \end{pmatrix} = [I_1 : -W_1]^{-1}$$

where $[I_1 : -W_1]$ is $m \times m$ optimal basis.

By equations (3) and (9),

(2) See Zellner-Theil [15], Jorgenson [4] or Madansky [9].

$$d = d^* + (BZ)^{-1}(A_1^* : A_2^*)' \begin{pmatrix} 0 \\ \dots \\ \bar{\lambda} \end{pmatrix} \tag{11}$$

where $(A_1^* : A_2^*)'$ is a columnwise rearranged A matrix such that

$$A'\lambda = (A_1^* : A_2^*)' \begin{pmatrix} 0 \\ \dots \\ \bar{\lambda} \end{pmatrix}.$$

d is an inequality constrained generalized least-squares (ICGLS) estimator vector.

By equations (8), (10), and (11),

$$d = (I + (BZ)^{-1} A_2^{*'} \cdot M_2 \cdot A) d^* - (BZ)^{-1} A_2^{*'} \cdot M_2 \cdot c \tag{12}$$

Since the optimal basis does not hold for all conceivable values of d^* except for the sufficiently large sample cases discussed in the next section, the covariance matrix of d is meaningful when the probability distribution of d^* is properly truncated. Such truncation is beyond the topic of this paper. Instead, the optimal basis obtained from a particular sample of d^* is imposed, and then an untruncated covariance matrix of d is derived.

$$V(d) \left| \begin{array}{l} \text{given} \\ \text{optimal} \\ \text{basis} \end{array} \right. = KV(d^*)K' \tag{13}$$

where

$$K = (I + (BZ)^{-1} A_2^{*'} M_2 A).$$

III. Useful Lemmas

The ICGLS estimator (d) depends on the generalized least-squares estimator (d^*), covariance matrix of residuals (Σ) and the dual vector (λ) at the optimal basis; i. e.,

$$d = d(d^*, \Sigma, \lambda) \tag{14}$$

The following Lemmas are useful for deriving further results.

Lemma 1. If Σ is a diagonal matrix, and all elements of λ are equal to zero, then the ICGLS estimate vector d reduces to a two-stage least-squares estimator (d_2).

Proof. From equations (3), and if $\lambda = 0$,

$$d = d^* = (Z'\bar{X}(\Sigma \times X'X)^{-1}\bar{X}'Z)^{-1}Z'\bar{X}(\Sigma \times X'X)^{-1}\bar{X}'y. \tag{15}$$

Since Σ is a diagonal matrix and $\bar{X}=(I \times X)$, d reduces to the following set of p equations

$$d_j = \sigma_{jj} (Z_j' X (X' X)^{-1} X' Z_j)^{-1} \left(\frac{1}{\sigma_{jj}} \right) (Z_j' X (X' X)^{-1} X' y_j) \quad (j=1, \dots, p)$$

where σ_{jj} , Z_j and y_j are j th diagonal element of Σ , j th submatrix of Z and j th subvector of y respectively.

Since all σ_{jj} s are cancelled out, d_j can be stacked as below;

$$d = (Z' \bar{X} (I \times X' X)^{-1} \bar{X}' Z)^{-1} Z' \bar{X} (I \times X' X)^{-1} y = d_2. \tag{16}$$

We state the following Lemmas since analogous proofs were given elsewhere. ⁽³⁾

Lemma 2. If Σ is a diagonal matrix and all elements of λ are strictly positive at the optimal solution, then the ICGLS estimate vector d reduces to an equality constrained two-stage least-squares estimate vector \bar{d}_2 ; i. e.,

$$d = d_2 + (B^* Z)^{-1} A' (A (B^* Z)^{-1} A')^{-1} (c - A d_2) = \bar{d}_2 \tag{17}$$

where

$$B^* \equiv Z' \bar{X} (I \times X' X)^{-1} \bar{X}'. \tag{18}$$

The covariance matrix of \bar{d}_2 becomes;

$$V(\bar{d}_2) = (B^* Z)^{-1} (I - A' (A (B^* Z)^{-1} A')^{-1} A (B^* Z)^{-1}). \tag{19}$$

Lemma 3. If Σ is a symmetric, positive definite matrix, and Σ is replaced by a two-stage estimate S of Σ , and if all elements of λ at the optimal basis are equal to zero, then the ICGLS estimate vector d reduces to a three-stage least-squares estimate vector d_3 ; i.e.,

$$d = (B^s Z)^{-1} B^s y = d_3 \tag{20}$$

where

$$B^s \equiv Z' \bar{X} (S \times X' X)^{-1} \bar{X}'. \tag{21}$$

Lemma 4. In Lemma 3, if all elements of λ at the optimal basis are strictly positive, the ICGLS estimate vector d reduces to an equality constrained three-stage least-squares estimate vector \bar{d}_3 ; i.e.,

$$d = d_3 + (B^s Z)^{-1} A' (A (B^s Z)^{-1} A')^{-1} (c - A d_3) = \bar{d}_3. \tag{22}$$

(3) For proofs for Lemmas (2-5), see Jorgenson [4], Theil [13] and Liew [7, 8], and for proofs for Lemmas (6-8), see Jorgenson [4], Madansky [9], Rothenberg-Leenders [11], Zellner-Theil [15] and Theil [13].

The covariance matrix of \bar{d}_3 becomes;

$$V(\bar{d}_3) = (B^s Z)^{-1} (I - A'(A(B^s Z)^{-1} A')^{-1} A(B^s Z)^{-1}). \quad (23)$$

Lemma 5. If the model (1) is exactly identifiable, and Σ is a diagonal matrix, the ICGLS estimate vector \bar{d} reduces to indirect least-squares estimate vector (\bar{d}_1) when the optimal $\lambda=0$, and the \bar{d} reduces to an equality constrained indirect least-squares estimate vector (\bar{d}_1) when the optimal $\lambda \gg 0$.

Lemma 6. Under usual assumptions, two-stage least-squares estimates \bar{d}_2 and three-stage least-squares estimates \bar{d}_3 are asymptotically unbiased and consistent estimates of δ .

Lemma 7. Under certain assumptions, equality constrained weighted least-squares estimates are best linear unbiased regression estimates under the linear prior restriction.

Lemma 8. The two-stage and three-stage least-squares estimates (\bar{d}_2 and \bar{d}_3) are the weighted least-squares estimates.

Lemma 9. The equality constrained two- and three-stage least-squares estimates (\bar{d}_2 and \bar{d}_3) are the equality constrained weighted least-squares estimates.

IV. Asymptotic Properties of the ICGLS Estimator

To show the asymptotic properties of the ICGLS estimates, we consider two cases; (1) all true parameters are unbounded (i. e., $A\delta \gg c$) and (2) some parameters are unbounded while the others are bounded (i. e., $A_1\delta \gg c_1$ and $A_2\delta = c_2$).

Theorem 1. If the prior belief ($A\delta \gg c$) is correct, then there exists a sufficiently large sample $n \geq n_0$ which makes all elements of dual vector λ zero at the optimal solution.

Proof. The solutions to the Dantzig-Cottle system ($v = W\lambda + q$, $v'\lambda = 0$, $\lambda \geq 0$ and $v \geq 0$) imply that when $q \gg 0$, all elements of λ become zero. To complete the proof, we need to show that there exists sufficiently large sample $n \geq n_0$ which makes all elements of q vector positive.

By relations (8), (9), (4) and (1)

$$q_n = A\delta - c + A \cdot \phi_n \quad (24)$$

where

$$\phi_n = (n^{-1}(Z'\bar{X})(\Sigma \times n^{-1}(X'X))^{-1}n^{-1}(\bar{X}'Z))^{-1} \cdot n^{-1}(Z'\bar{X})(\Sigma \times n^{-1}(X'X))^{-1}n^{-1}\bar{X}'\epsilon. \quad (25)$$

Subscript n denotes the sample size. With the usual assumptions of the asymptotic sampling theory, we can show that ϕ_n vanishes as the sample size increases sufficiently large.⁽⁴⁾ If the prior belief is correct, $A\delta - c \gg 0$ and it remains constant whereas $A\phi_n$ is getting smaller as the sample size n increases. Therefore, there exists a sufficiently large sample $n \geq n_0$ which makes $q_n \gg 0$.

Corollary 1. If the prior belief $(A\delta - c \gg 0)$ is correct and Σ is a diagonal matrix, then the ICGLS estimate vector d becomes an asymptotically unbiased and consistent estimator of δ . In this case, the untruncated covariance matrix of d shares the same asymptotic properties of the covariance matrix of two-stage least-squares estimates.

Proof. Theorem 1 states that there is a sufficiently large sample $n \geq n_0$ which makes $q_n \gg 0$ and $\lambda = 0$. Lemma 1 states that if Σ is a diagonal matrix and $\lambda = 0$, the ICGLS estimate vector d reduces to the two-stage least-squares estimate vector d_2 which is asymptotically unbiased and consistent estimator of δ by Lemma 6.

Corollary 2. If the prior belief $(A\delta - c \gg 0)$ is correct and Σ is replaced by a consistent estimate S obtained from the two-stage estimates, then ICGLS estimate vector d shares the same asymptotic properties of three-stage least-squares estimate vector d_3 . In this case, the untruncated covariance matrix of d shares the same asymptotic properties of the covariance matrix of d_3 .

Proof. By Theorem 1 and Lemma 3, we can show that there exists a sufficiently large sample $n \geq n_0$ which reduces d to d_3 .

Next we consider the case where some parameters are bounded and some are unbounded (i.e., $A_1\delta \gg c_1$ and $A_2\delta = c_2$).

(4) See Jorgenson [4].

Theorem 2. If the prior belief $(A_1\delta \gg c_1$ and $A_2\delta = c_2)$ is correct, then there exists a sufficiently large sample $n \geq n_0$ such that the ICGLS estimate vector d reduces to an equality constrained generalized least-squares (ECGLS) estimators (\vec{d}).

Proof. In this case, the sample estimates (d) have two constraints; (1) $A_1d \geq c_1$ and (2) $A_2d = c_2$. The equations (2) and (3) are partitioned as below:

$$A_1d - v_1 = c_1 \tag{26}$$

$$A_2d = c_2 \tag{27}$$

$$(A_1' : A_2') \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} + By = BZd \tag{28}$$

where

$$B \equiv Z' \bar{X} (\Sigma \times X'X)^{-1} \bar{X}'$$

By equations (27) and (28),

$$\lambda_2 = -W_{22}^{-1} W_{21} \cdot \lambda_1 - W_{22}^{-1} (A_2(BZ)^{-1} By - c_2) \tag{29}$$

where

$$W_{ij} \equiv A_i(BZ)^{-1} A_j' \quad i, j = 1, 2.$$

By equations (26) and (28),

$$v_1 = W_{11}\lambda_1 + W_{12}\lambda_2 + A_1(BZ)^{-1} By - c_1. \tag{30}$$

By equations (29) and (30),

$$v_1 = M^* \lambda_1 + q^* \tag{31}$$

where

$$M^* = W_{11} - W_{12} \cdot W_{22}^{-1} \cdot W_{21} \tag{32}$$

$$q^* = -W_{12} \cdot W_{22}^{-1} \cdot (A_2(BZ)^{-1} By - c_2) + (A_1(BZ)^{-1} By - c_1). \tag{33}$$

Since $y = Z\delta + \varepsilon$,

$$(BZ)^{-1} By = \delta + (BZ)^{-1} B\varepsilon. \tag{34}$$

Let q_n^* be the q^* on sample size n . By equations (33) and (34), the following relation is evident.

$$\bar{b}_n^* = (A_1\delta - c_1) - W_{12} W_{22}^{-1} (A_2\delta - c_2) + (A_1 - W_{12} W_{22}^{-1} A_2) (B_n Z_n)^{-1} B_n \varepsilon \tag{35}$$

where

$$(B_n Z_n)^{-1} B_n \epsilon \equiv (n^{-1} Z' \bar{X} (\Sigma \times n^{-1} X' X)^{-1} n^{-1} \bar{X}' Z)^{-1} \cdot n^{-1} Z' \bar{X} (\Sigma \times n^{-1} X' X)^{-1} n^{-1} \bar{X}' \epsilon. \tag{36}$$

The second term of equation (35) vanishes because of the prior information (i. e., $A_2 \delta - c_2 = 0$) and the third term is getting smaller under usual assumptions of the asymptotic sampling theory as sample size is getting larger.⁽⁵⁾ The first term is positive and remains constant as sample size increases. Therefore, there exists a sufficiently large sample $n \geq n_0$ which makes $q_n^* \gg 0$. The subscript n hereafter is deleted for notational simplification.

When $q^* \gg 0$, the Dantzig-Cottle solutions are;

$$v_1 = q^* \gg 0 \text{ and } \lambda_1 = 0. \tag{37}$$

By equations (28), (29) and (37),

$$d = d^* + (BZ)^{-1} A'_2 (A_2 (BZ)^{-1} A'_2)^{-1} (c_2 - A_2 d^*) = \bar{d} \tag{38}$$

where

$$d^* = (BZ)^{-1} B y.$$

Corollary 3. If the prior belief $(A_1 \delta \gg c_1$ and $A_2 \delta = c_2)$ is correct and Σ is a diagonal matrix, then there exists a sufficiently large sample $n \geq n_0$ such that the ICGLS estimate vector d reduces to an equality constrained two-stage least-squares estimate vector \bar{d}_2 . In this case, the ICGLS estimate d is the best linear unbiased regression under the linear prior restriction and the untruncated covariance of d shares same statistical properties of the covariance matrix of (\bar{d}_2) .

Proof. It follows immediately from the proofs of Theorem 2, Lemmas 1, 7, 8 and 9.

Corollary 4. In the Corollary 3, if Σ is replaced by a consistent estimate S from two-stage least-squares estimates, then there exists a sufficiently large sample $n \geq n_0$ such that the ICGLS estimate vector d reduces to an equality constrained three-stage least-squares estimate vector \bar{d}_3 . Therefore, the ICGLS estimate vector d and its covariance matrix $(V(d))$ shares the

(5) See Jorgenson [4].

same asymptotic properties of equality constrained three-stage least-squares estimate vector \bar{d}_3 and their covariance matrix $(V(\bar{d}_3))$.

Proof. It follows immediately from the proofs of Theorem 2, Lemmas 3, 7 and 8.

V. A Numerical Example

Suppose we have the following new demand and supply model for electricity in the United States.

Demand Equation

$$\log q_i = \log \alpha_0 + \alpha_1 \log p_i + \alpha_2 \log \pi_i + \alpha_3 \log y_i + \varepsilon_{1i}$$

Supply Equation

$$\log p_i = \log \beta_0 + \beta_1 \log q_i + \beta_2 \log z_i + \varepsilon_{2i}$$

where

q_i is the new demand for electricity (KWH) for i th state in 1970.

p_i is the price of electricity (\$) per KWH for i th state in 1970.

π_i is the price of natural gas per Therm for i th state in 1970.

y_i is the expenditure on new demands for electricity and natural gas (i.e., $y_i = p_i q_i + \pi_i G_i$) where G_i is the new demand for natural gas for i th state in 1970.

z_i is a proxy to the capacity for the new supply of electricity. Installed electricity generating capacity (million KWH) was used in the computation as a proxy to the capacity. ε_{1i} and ε_{2i} are residuals.

To maintain structural consistency, the following restrictions were made:

Demand Equation

- (i) $\alpha_1 \leq 0$ (negative demand price elasticity)
- (ii) $\alpha_2 \geq 0$ (positive cross-elasticity)
- (iii) $\alpha_3 \geq 0$ (positive income elasticity)
- (iv) $\alpha_1 + \alpha_2 + \alpha_3 = 0$ (the homogeneity condition)

Supply Equation

- (i) $\beta_1 \geq 0$ (positive supply price elasticity)

(ii) $\beta_2 \leq 0$ (negative capacity elasticity with respect to price)

Utilizing 51 observations, we calculate parameters of the electricity model. We obtain the following empirical results.⁽⁶⁾

Demand Equation

Parameters	Two-Stage Estimate		ICGLS Estimate*	
	Estimate	Std. Error	Estimate	Std. Error
log α_0	-0.9865	0.5046	-0.2910	0.5097
α_1	-1.3652	0.1366	-1.1812	0.1269
α_2	0.2219	0.0499	0.2325	0.0532
α_3	0.9417	0.0159	0.9487	0.0163

Supply Equation

Parameters	ICGLS and Two-Stage Estimate**	
	Estimate	Std. Error
log β_0	-6.3088	1.1045
β_1	0.3482	0.1504
β_2	-0.3818	0.1442

The Estimated Variance-Covariance Matrix of the ICGLS Estimates

.25983	.06279	.00989	.00071
	.01612	.00130	.00041
		.00283	.00024
			.00027

* ICGLS estimate when Σ is a diagonal matrix.

** None of the constrained is bounded, the ICGLS estimate is same as the two-stage estimate.

Sources of Data: The data were collected from the following sources: (a) U.S. Department of Commerce, *Statistical Abstract of the U. S.*, Washington, D. C.: U.S. Government Printing Office, 1971, 1972 and 1974. (b) U. S. Federal Power Commission, *Statistics of Privately-Owned Electric Utilities in the United States*, Washington, D. C.: U.S. Government Printing Office, 1969 and 1970. (c) U. S. Federal Power Commission, *Statistics of Publicly-Owned Electric Utilities in the United States*, Washington, D. C.: U. S. Government Printing Office, 1969 and 1970.

The new demand for electricity (q_i) and for natural gas (g_i) was estimated as below:

$$q_i(1970) = Q_i(1970) - 0.9 Q_i(1969)$$

$$g_i(1970) = G_i(1970) - 0.9 G_i(1969)$$

where $Q_i(1970)$ is per capita electricity consumption in i th state during 1970 and $G_i(1970)$ is per capita natural gas consumption in i th state during 1970.

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